

AMENDMENTS TO THE CLAIMS:

The following listing of claims will replace all prior versions, and listings, of claims in the application:

Page 13, line 1, before claim 1, replace the single word heading CLAIMS with the following heading:

CLAIMS WHAT IS CLAIMED IS:

1. (Currently Amended) Tear-off device for sections ~~(48)~~ of a continuous material, comprising: ~~(18)~~ with

a pullout mechanism ~~(10)~~ for the transport of the continuous material ~~(18)~~ and with

a tear-off mechanism ~~(12)~~, which has at least two pressure-applying elements ~~(26, 56)~~, which are disposed on opposite sides of the continuous material ~~(18)~~ and a positioning device of which for engaging at least one said pressure-applying element can be positioned against the continuous material (18) by a positioning device, characterized in that the engagable pressure-applying elements (26, 56) are being constructed as eccentric rollers and being adapted to can be driven one of:

individually or and

jointly.

2. (Currently Amended) The tear-off device of claim 1,
~~wherein characterized in that~~ the engagable pressure-applying
elements have internal eccentrics {28, 30}, which are adapted to
can be rotated and on which the pressure-applying rollers {26}
are mounted rotatably.

3. (Currently Amended) The tear-off device of claim 1,
~~wherein characterized in that~~ the engagable, pressure-applying
elements {56} have cams {58}, which are adapted to can be engaged
against the continuous material {18}.

4. (Currently Amended) The tear-off device of claim 3,
~~wherein characterized in that~~ the cams {58} have the shape of
roller segments.

5. (Currently Amended) The tear-off device of claim 1,
~~wherein one of the preceding claims, characterized in that~~ the
positioning device has at least one motor {36}, by means of which
for driving the pressure-applying elements {26, 56} can be
driven.

6. (Currently Amended) The tear-off device of claim 5,
~~wherein characterized in that~~ the positioning device has a
control device {42} for the temporal control of the movement of

the motor (36).

7. (Currently Amended) The tear-off device of claim 6,
~~wherein characterized in that~~ the control device (42) is a
programmable control device, ~~with which the for adjusting points~~
in time of ~~the at least one of~~ engagement and/or withdrawal
movements ~~can be adjusted~~ in relation to the transport of the
continuous material (18).

8. (Currently Amended) The tear-off device of claim 6, one
~~of the claims 6 or 7, wherein characterized in that~~ the at least
one motor (36) of the positioning device is adapted to ~~can be~~
driven over a limited traversing distance in opposite directions
and ~~the~~ adjusting movements of the at least one motor (36) ~~can~~
are adapted to be controlled temporally by the control device
(42) and, ~~in the case of a programmable control device (42), the~~
~~traversing distance of the motor (36) can be programmed.~~

9. (Currently Amended) The tear-off device of claim 5,
~~wherein one of the claims 5 to 7, characterized in that~~ the at
least one motor (36) can is adapted to be driven in one direction
of rotation with a variable speed.

10. (Currently Amended) The-tear off device of claim 9,
~~characterized in that wherein~~ the speed of the at least one motor
(36) ~~can~~ is adapted to be varied down to zero.

11. (Currently Amended) The-tear off device of claim 5, ~~one of the claims 5 to 10, characterized in that wherein~~ the at least one motor (36) is a servomotor.

12. (Currently Amended) The tear-off device of claim 1,
~~wherein one of the preceding claims, characterized in that~~ the pullout mechanism (10) and the tear-off mechanism (12) each have their own driving mechanism (22).

13. (Currently Amended) The tear-off device of claim 1,
~~wherein one of the preceding claims, characterized in that~~ the positioning device has at least one displaceable frame (32), in which at least one or more pressure-applying element is elements (26, 56) ~~are~~ mounted.

14. (New) The tear-off device of one of the claim 8,
wherein the control device is a programmable control device for controlling a traversing distance of the at least one motor.